# S1C17 Family Application Note S1C17M01/W22/W23 Peripheral Circuit Sample Software

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# **Table of Contents**

1.	Ov	erview	1
-	.1	Operating Environment	1
2.	Sa	mple Software Configuration	2
2	2.1	Directory Structure and File Composition	2
3	Fx	ecution Method	4
0.	 1	Software Development Environment	4
	3.2	Installing each Tool	4
	3.3	Importing Project	5
	3.3.	.1 Importing Sample Program (Common to GNU17 version 2 and version 3)	5
	3.3.	.2 Importing Sample Program (GNU17 version 2)	7 11
•	3.J.	Connecting with Target	
	<del>.</del> 3.5	Operating ICDmini and Target	
	3.5.	.1 When ICDmini ver. 2.0 is Used	16
	3.5.	.2 When ICDmini ver. 3.0 is Used	17
	8.6	Building Project and Starting Debugger	18
	3.6	2 When GNU17 version 2 is Used	. 18 19
4	Do	taila af Samala Saftwara Eurotian	20
4.		Uails of Sample Software Function	.20 20
-	4.1.	.1 Sample Software Specification	20
	4.1.	2 Hardware Conditions	20
	4.1.	3 Operations Overview	21
4	.2 ⊿ 2	Clock Generator (CLG) [Common to S1C17M01/W22/W23]	22
	4.2	.2 Hardware Conditions	22
	4.2.	.3 Operations Overview (S1C17M01)	22
	4.2.	4 Operations Overview (S1C17W22/W23)	24
4	l.3 ⊿ 3	16-Bit Timer (T16) [Common to S1C17M01/W22/W23]	<b>26</b>
	4.3	.2 Hardware Conditions	20
	4.3.	.3 Operations Overview	26
4	1.4	16-Bit PWM Timer (T16B) [Only for S1C17W22/W23]	27
	4.4. 4.4	.1 Sample Software Specification	27 27
	4.4	.3 Operations Overview	27
4	.5	Real Time Clock (RTCA) [Common to S1C17M01/W22/W23]	29
	4.5.	.1 Sample Software Specification	29
	4.5. 4.5	2 Hardware Conditions	29 20
2	ч.J.	Watchdog Timer (WDT) [Common to S1C17M01/W22/W23]	
	4.6.	.1 Sample Software Specification	30
	4.6	.2 Hardware Conditions	30
	4.6.		30
4	4.7	UAK I (UAK I) [COMMON to S1C1/MU1/W22/W23]       1     Sample Software Specification	<b>31</b> 31
	4.7.	.2 Hardware Conditions	31
	4.7.	.3 Operations Overview	31

4.8 SI	PI (SPI) [Common to S1C17M01/W22/W23]	32
4.8.1	Sample Software Specification	32
4.8.2	Hardware Conditions	32
4.8.3	Operations Overview	32
4.9 I2	C (I2C) [Common to S1C17M01/W22/W23]	33
4.9.1	Sample Software Specification	33
4.9.2	Hardware Conditions	33
4.9.3	Operations Overview	33
4.10 L0	CD driver (LCD8A) [Only for S1C17M01]	34
4.10.1	Sample Software Specification	34
4.10.2	Hardware Conditions	34
4.10.3	Operations Overview	34
4.11 LO	CD driver (LCD24A) [Only for S1C17W22]	35
4.11.1	Sample Software Specification	35
4.11.2	Hardware Conditions	35
4.11.3	Operations Overview	35
4.12 R/	F Converter (RFC) [Common to S1C17M01/W22/W23]	36
4.12.1	Sample Software Specification	
4.12.2	Hardware Conditions	
4.12.3		
4.13 So	bund Generator (SNDA) [Only for S1C17W22/W23]	37
4.13.1	Sample Software Specification	37
4.13.2	Charations Overview	31 27
4.13.3		
4.14 M	R Sensor Controller (AMRC) [Only for S1C1/M01]	
4.14.1	Sample Sonware Specification	38 20
4.14.2	Operations Overview	
4.45 D	Operations Overview	
4.15 PC	Sample Software Specification Circuit (SVD) [Common to S1C1/M01/W22/W23]	
4.15.1	Hardware Conditions	
4 15 3	Operations Overview	
116 D	wer Concreter (PWC2) [Only for \$1017W22/W22]	40
4.10 FU	Sample Software Specification	<b>40</b>
4.10.1	Hardware Conditions	40
4 16 3	Operations Overview	40
117 EI	EPPOM [Only for \$1C17M01]	
4.17 1	Sample Software Specification	<b>41</b>
4 17 2	Hardware Conditions	
4.17.3	Operations Overview	
4 18 AI	C Comparator [Only for S1C17W23]	42
4 18 1	Sample Software Specification	42
4.18.2	Hardware Conditions	
4.18.3	Operations Overview	42
4.19 R	EMC [Common to S1C17W22/W23]	44
4,19,1	Sample Software Specification	
4.19.2	Hardware Conditions	
4.19.3	Operations Overview	44
Rovision	History	16
1/2412101	- 1 II 3.01 y	40

# 1. Overview

This manual describes the usage and behavior of the sample software for S1C17M01, S1C17W22, and S1C17W23.

The S1C17M01/W22/W23 sample software is intended to show usage examples of peripheral circuits embedded in the S1C17M01 and S1C17W22/W23 microcontrollers.

Refer to this document along with various model information, each technical manual, and S5U1C17001C Manual.

## 1.1 Operating Environment

Before running the S1C17M01/W22/W23 sample software, prepare the following components:

- Board equipped with an S1C17M01 or S1C17W22/W23
- S5U1C17001H (hereinafter referred to as "ICDmini")
- S5U1C17001C (hereinafter referred to as "GNU17")

Notes: • The operational check of this sample software is carried out in GNU17 v2.3.0/v3.0.5.

• There are multiple versions of GNU17 and ICDmini. For the ICDmini supported by the GNU17 to be used, refer to the S5U1C17001C Manual.

# 2. Sample Software Configuration

This chapter describes the file configuration of the S1C17M01/W22/W23 sample software.

The S1C17M01/W22/W23 sample software is composed of "Sample software" for checking the behavior of each peripheral circuit and "Sample driver" for controlling each peripheral circuit.

## 2.1 Directory Structure and File Composition

The following shows the directory structure of the S1C17M01/W22/W23 sample software:

[s1c17m01_w22_w23_xxx_sample] [inc_m01] : Header files for S1C17M01 c17m01_reg.h [reg] clg_reg.h wdt_reg.h
<pre> [inc_w22] : Header files for S1C17W22 [ c17w22_reg.h [ reg]</pre>
<pre>[inc_w23] : Header files for S1C17W23</pre>
<pre> [s1c17m01_w22_w23_xxx_gnu17v2] : Sample software (GNU17 version 2 project) GNU17 project files, etc [inc] : Empty directory for storing header files for each model [src] : Source codes and header files [src] : Source codes and header files [init.c] init.c init.h main.c</pre>
<pre>[s1c17m01_w22_w23_xxx_gnu17v3] : Sample software (GNU17 version 3 project) GNU17 project files, etc.  [inc] : Empty directory for storing header files for each model [src] : Source codes and header files boot.c init.c init.h  main.c</pre>

Figure 2.1.1 Directory structure of S1C17M01/W22/W23 sample software

(1) s1c17m01\_w22\_w23\_xxx\_sample, s1c17m01\_xxx\_sample, s1c17w22\_w23\_xxx\_sample, and s1c17w23\_xxx\_sample directories

These directories contain the sample software.

(2) inc\_m01, inc\_w22, and inc\_w23 directories

These directories contain the header files in which the model dependent information such as the registers of the S1C17M01 and S1C17W22/W23 are defined.

- Header file which defines the register address and other information of S1C17M01 (c17m01 reg.h)
- Header file which defines the register address and other information of S1C17W22 (c17w22\_reg.h)
- Header file which defines the register address and other information of S1C17W23 (c17W23\_reg.h)
- (3) reg directory

This directory contains the header files in which the control bit assignments for each peripheral circuit are defined.

- Header files which define the control bit assignments for each peripheral circuit (clg\_reg.h, etc.)
- (4) s1c17m01\_w22\_w23\_xxx\_gnu17vx, s1c17m01\_xxx\_gnu17vx. s1c17w22\_w23\_xxx\_gnu17vx, and s1c17w23\_xxx\_gnu17vx directories

These directories contain the files which pertain the GNU17 project.

"\_gnu17v2" and "\_gnu17v3," the last part of the directory names, represent the GNU17 version.

(5) inc directory

This directory is used to place the header files to be used for the project by copying from directories (2) and (3).

(6) src directory

This directory contains microcontroller initialization programs, sample programs and drivers for controlling the peripheral circuits, and the header files in which the constants and other items used in the sample programs and drivers are defined.

- File that contains vector table and initialization processing (boot.c)
- Sample software file for each peripheral circuit (main.c)
- Sample driver files for each peripheral circuit (init.c, clg.c, etc.)
- Sample driver header files for each peripheral circuit (init.h, clg.h, etc.)

## 3. Execution Method

# 3. Execution Method

## 3.1 Software Development Environment

This chapter describes the software development environment using the following tools. For more information on each tool, refer to each tool manual.

- S5U1C17001C (GNU17) ver. 2.3.0/ver. 3.05
- Model information files (S1C17M01, S1C17W22, S1C17W23)
- S5U1C17001H (ICDmini) ver. 2.0/ver. 3.0

## 3.2 Installing each Tool

(1) GNU17 version 2/version 3 (S5U1C17001C)

- Download the compressed GNU17 file from the Epson MCU users site.
- https://www.epsondevice.com/support\_e/mcu/product/c17.html
- Decompress the compressed GNU17 file into any folder.
- Run Setup.exe to install GNU17.

(2) Install the model information files

- Confirm and download the latest model information files from the Epson MCU users site. <u>https://www.epsondevice.com/support\_e/mcu/product/page04.html#02</u>
- Decompress the downloaded model information files into the [mcu\_model] subfolder of the folder where GNU17 is installed.

Example: When the S1C17M01 model information files are added



Figure 3.2.1 Adding model information files for S1C17M01

- (3) ICDmini ver. 2.0 (S5U1C17001H)
  - After installing GNU17 version 2, connect between the ICDmini and the PC with the USB cable.
  - Install the USB driver, that exists in the folder where the GNU17 was installed, to the PC. When the GNU17 was installed in the C:\EPSON\GNU17 directory, the USB driver was placed into the directories shown below.

For 32-bit OS: C:\EPSON\GNU17\utility\drv\_usb\OS\_32bit For 64-bit OS: C:\EPSON\GNU17\utility\drv\_usb\OS\_64bit

#### (4) ICDmini ver. 3.0 (S5U1C17001H)

- After installing GNU17 version 3, connect between the ICDmini and the PC with the USB cable.
- Install the USB driver, that exists in the folder where the GNU17 was installed, to the PC. When the GNU17 was installed in the C:\EPSON\GNU17V3 directory, the USB driver was placed into the C:\EPSON\GNU17V3\utility\drv\_usb\Mini3Driver directory.

## 3.3 Importing Project

This section describes how to import the sample program into GNU17.

- Notes: For more information on importing programs, refer to the S5U1C17001C Manual.
  - The program import procedure between GNU17 version 2 and version 3 is different.

#### 3.3.1 Importing Sample Program (Common to GNU17 version 2 and version 3)

(1) Launch GNU17 IDE

Double-click the eclipse.exe icon in the eclipse sub-directory of the directory where GNU17 was installed to launch IDE. IDE is also launched by selecting [EPSON MCU] > [GNU17] > [GNU17 IDE] ([EPSON MCU] > [GNU17V3] > [GNU17V3 IDE] in GNU17 version 3) from the Windows startup menu.

(2) Decompress sample program

Decompress the sample program downloaded from the Epson MCU users site.

(3) Copy the header files for each model

Copy the header files for each model to the sample software's project folder.

Example: Clock generator sample program [s1c17m01\_w22\_w23\_clg\_gnu17vx]

The files under the [inc\_m01] subfolder of the folder where s1c17m01\_w22\_w23\_clg\_sample is decompressed are the header files for S1C17M01, and the files under the [inc\_w22] subfolder and [inc\_w23] subfolder are the header files for S1C17W22 and S1C17W23. Copy these files to the sample software's [inc] folder according to the target used.

For example, if the target is [S1C17M01], copy the [c17m01\_reg.h] file and [reg] folder under [inc\_m01] subfolder.



Figure 3.3.1 Copying S1C17M01 header files

Place the copied header files into [inc] subfolder in the sample software's [s1c17m01\_w22\_w23\_clg\_gnu17vx] folder, as shown below:



Figure 3.3.2 Pasting S1C17M01 header files

(4) Editing the header file

Edit the sample software header file [inc\init.h] according to the target CPU. Uncomment the #include line for the target CPU written under [// MCU select].

Example: When using the S1C17M01 sample software

// MCU select
#include MCUSEL\_C17M01
//#include MCUSEL\_C17W22
//#include MCUSEL\_C17W23

Example: When using the S1C17W22 sample software

// MCU select

//#include MCUSEL\_C17M01

#include MCUSEL\_C17W22

//#include MCUSEL\_C17W23

#### 3.3.2 Importing Sample Program (GNU17 version 2)

#### (1) Import sample program

Select [Import...] from the GNU17 [File] menu. In the [Import] wizard, select [General] > [Existing Project to Workspace].

Tmport	
Select	r <sup>2</sup> 1
Create new projects from an archive file or directory.	
<u>S</u> elect an import source:	
type filter text	
🔺 😂 General	<b>^</b>
Archive File	=
Existing Projects into Workspace	
📮 File System	
References	-
⑦ < <u>B</u> ack <u>N</u> ext > <u>F</u> inish	Cancel

Click the [Browse...] button at the right of [Select root directory:] and select the [xxx\_gnu17v2] project in the sample project folder decompressed in step (2) of Section 3.3.1.

🐠 Import		- <b>x</b>				
Import Projects						
Select a directory to sea	rch for existing Eclipse projects.					
Colort vo at divartan v		Drawa				
Select roo <u>t</u> directory.	C.\stc17xxx_xxx_sample\stc17xxx_xxx_ghu17vz	D <u>I</u> Owse				
Select <u>archive file</u> :		B <u>r</u> owse				
<u>P</u> rojects:						
s1c17xxx_xxx_gnu	17v2 (C:\s1c17xxx_xxx_sample\s1c17xxx_xxx_gnu17v2)	<u>S</u> elect All				
		Deselect All				
		R <u>e</u> fresh				
☑ Copy projects into workspace						
0	< <u>B</u> ack <u>N</u> ext > <u>Finish</u>	Cancel				

Select the [Copy projects into workspace] checkbox. This enables to create the project's copy in the workspace directory, thereby not changing the original files. Finally, click the [Finish] button. Check to see in GNU17 that the sample project has been imported and then remove the folder decompressed in step (2) of Section 3.3.1.

#### (2) Change the target

Change the target for the sample program. Select the sample program's project in the "C/C++ project" view and select [Properties] in the [Project] menu.

In the [Properties for ...] dialog, select [GNU17 General].

Properties for s1c17xxx_xxx_	gnu17v2
type filter text	GNU17 General $\diamond \bullet \bullet \bullet$
Resource Builders C/C++ General C/C++ Include Paths and C/C++ Make Project C/C++ Project Paths GNU17 Build Options GNU17 Flash Settings GNU17 GDB Commands GNU17 GDB Commands GNU17 GDB Commands GNU17 General GNU17 Commands GNU17 Parameter Setting GNU17 Unused functions Project References Run/Debug Settings	Target program         Application(.psa/.elf)         Target CPU Device         \$S1C17W22         Memory Model         REGULAR         Regular use. Locate program in 16MB (24 bit) area.         Co-processor Libraries         ✓ Use Co-processor Library         Select the Co-processor library type:         Multiplication/Division2 (libc ▼         NOTE : To use Co-processor library, please assign 'emu_copro_process()' to interrupt vector No.3
• ا	Revert Settings
0	OK Cancel

In the [Target CPU Device], select a target CPU and click the [OK] button.

For example, if the target CPU is S1C17W22, change the Target CPU Device to "S1C17W22."

(3) Set the debugger's startup options

Set the Startuo options for the debugger. Select the sample program's project in the "C/C++ project" view and select [Properties] in the [Project] menu.

In the [Properties for ...] dialog, select [GNU17 GDB Commands].

Properties for s1c17xxx_xx	_gnu17v2
type filter text	GNU17 GDB Commands 🗢 👻 🔶
Resource Builders C/C++ General C/C++ Include Paths and C/C++ Make Project C/C++ Project Paths GNU17 Build Options GNU17 Flash Settings GNU17 GDB Commands GNU17 GDB Commands GNU17 General GNU17 Commands GNU17 Parameter Settin GNU17 Parameter Settin GNU17 Unused function Project References Run/Debug Settings	Contents of s1c17xxx_xxx_gnu17v2_gnu17IDE.cmd can be edited here These commands will be written to s1c17xxx_xxx_gnu17v2_gnu17IDE.cmd when OK or Apply is pressed # Command file generated by Gnu17 Plug-in for Eclipse # load debugging information in program file s1c17xxx_xxx_gnu17v2.elf # set the memory configuration map file to the debugger c17 rpf s1c17xxx_xxx_gnu17v2_gnu17IDE.par # connect to the debugger with specified mode and port # target [icd usb   sim] target icd usb # load program to memory load s1c17xxx_xxx_gnu17v2.elf # reset c17 rst
4 111	<u>Revert Settings</u> <u>Apply</u>
0	OK Cancel

This page displays the contents of the debugger startup command file that will be generated by the IDE.

The debugger must be set to the appropriate mode that suits the ICD used, etc. before it can be operated.

The debugger startup command file should be created with a procedure shown below.

Click the [Create commands from template] button to display the [Create a simple startup command] dialog. Select "ICD Mini" from the [Debugger:] combo box.

🐠 Create a simple	e startup command	×
Create a simple	e startup command	
This will create a NOTE: Your curr	a simple startup command with the following configuration. rently edited commands will be replaced.	
	Specify the Method of generating command file	
	<ul> <li>Use the command file that depends on machin</li> <li>Use the following settings</li> </ul>	
	Settings	
	Debugger: ICD Mini   Execute floor	
	Boot vector address 008000	
	Ports	
	Connect Port USB	
0	<u>Qverwrite</u> <u>C</u> lose	

Click the [Overwrite] button, then click the [OK] button in the [Overwrite commands] dialog displayed next. The commands may be added and edited directly in this page as necessary.

\* Precautions on using a simulated I/O

When using the debugger's simulated I/O (to evaluate the external input/output functions such as a serial interface using a standard input/output (stdin, stdout) or by inputting/outputting a file), append the following lines to the GDB command file.

# After last line "c17 rst", add following three lines

u main

```
c17 stdout 1 WRITE_FLASH WRITE_BUF
```

c17 stdin 1 READ\_FLASH READ\_BUF

The sample programs using simulated I/O are as follows.

- Clock generator (CLG) [S1C17M01/W22/W23 common]
- 16 bit PWM timer (T16B) [S1C17W22/W23 exclusive use]
- ADC, Comparator [S1C17W23 exclusive use]

## 3.3.3 Importing Sample Program (GNU17 version 3)

(1) Importing the sample program

Select [Import...] from the [File] menu of GNU17 to start the [Import] wizard, and then select [General] > [Existing Projects into Workspace].

€ Import	- <b>.</b> X
Select	Ľ
Create new projects from an archive file or directory.	
<u>S</u> elect an import source:	
type filter text	
🔺 🗁 General	<b>^</b>
I Archive File	
Existing Projects into Workspace	
📮 File System	
GNU17 V2 Project	+
(?) < Back Next > Einish	Cancel
	cuncer

## 3. Execution Method

Click the [Browse...] button at the right of [Select root directory:] and select the [xxx\_gnu17v3] project in the sample project folder decompressed in step (2) of Section 3.3.1.

Import								
Import Projects	Import Projects							
Select a directory to sea	ch for existing Eclipse proj	ects.						
	C) 1 17	4 47	17.2		-			
Select root directory:	C:\s1c1/xxx_xxx_sample\s	1c1/xxx_xxx_gnu	17V3	▼ [	Browse			
Select <u>a</u> rchive file:				-	B <u>r</u> owse			
<u>P</u> rojects:								
s1c17xxx_xxx_gnu1	7v3 (C:\s1c17xxx_xxx_samp	ole\s1c17xxx_xxx_	gnu17v3)		Select All			
					Deselect All			
					R <u>e</u> fresh			
<ul> <li>Search for nested provide the search for nested provide the search for nested projects into we find the search for the search fo</li></ul>	jects orkspace eady exist in the workspace	2						
Working sets	ng sets							
W <u>o</u> rking sets:	Working sets: Select							
0	< <u>B</u> ack <u>N</u>	ext >	<u>F</u> inish		Cancel			

Select the [Copy projects into workspace] checkbox. This enables copying of the project into the workspace directory so that the original files will not be modified. Finally, click the [Finish] button. After making sure that the sample project has been imported to GNU17, the folder decompressed in the step (2) of Section 3.3.1 can be removed.

#### (2) Select the target CPU

The target CPU to run the sample program should be selected. Select the sample project in the [Project Explorer] view and select [Properties] from the [Project] menu to open the [Properties] dialog. Select [GNU17 Settings] from the property list on the dialog.

Properties for s1c17	7xxx_xxx_gnu17v3			- • ×
type filter text	GNU17 Setting			⇔ ▼ ⇔ ▼ ▼
<ul> <li>Resource</li> <li>Builders</li> </ul>	Target CPU	S1C17W22 -		
<ul> <li>C/C++ Build</li> <li>C/C++ General</li> </ul>	Memory Model REGULAR : Locate program in 16MB (24 bit) area	REGULAR 🔻		
GNU17 Setting	SMALL : Locate program in 64KB (16 bit) area.			
Project References	GCC Version	4.9 -		
Run/Debug Settin  Task Repository				
WikiText				
۰ III ۲			Restore <u>D</u> efaults	Apply
0			OK	Cancel

Select a target CPU from the [Target CPU] dropdown list, for example, select "S1C17W22" if it is the target CPU, and click the [Apply] button. Then click the {OK] button to close the dialog.

(3) Setting the debugger startup options

The debugger startup options should be selected. Expand the sample project in the [Project Explorer] view and open [gdbmini3.ini] with the editor.

Elle Edit Source Refaçor Navigate Search Project Bun Window Help   Quick Access @ @ @C/C++ Opicet Explorer % @ @ @ @ @ @ @ @ @ @ @ @ @ @ @ @ @ @	C/C++ - s1c17xxx_xxx_gnu17v3/gdbmini3.ini - Edipse							
Image: Start Star	<u>File Edit Source Refactor Navigate Se</u>	arch <u>P</u> roject <u>R</u> un <u>W</u> indow <u>H</u> elp						
Project Explorer R: Project Explorer P: Pro	<b>□ ▼</b>	· C ▼ G ▼   ☆ ▼ O ▼ 9: ▼ 9: ▼ 12 0 0 0 0 ▼ 12 11 12 ▼ 8: ▼	• • • • •			Quick Access	🖻 🖻 🕻	C/C++
0 items <i>items</i> Description         Resource           Register         Hex           Bin         Reset           Ac	Project Explorer R     Project Explorer R     Solution     Soluti	<pre>d</pre>	es to enab	le STDOUT while debuggin	g.	Quick Access	E Task	
Vescription     Resource     Registeri     ritex     Dirit     Reset     Ac		0 items	D	EKKOK: Please select a chip u	Ising the	preterence page (c++/De	bug/EmbS	ys Reg
		Description	Resource	Register	nex	DITI	neset	MC
	< >	•	Þ	•				•

The editor displays the contents of the debugger startup command file. The debugger must be set to the appropriate mode that suits the microcontroller and ICD used.

\* Precautions on using the standard output

When using the standard output, uncomment (remove #) the command lines of the GDB command file as shown below (the lines highlighted in red) to enable them to be executed.

GDB command file [gdbmini3.ini]

```
# Please uncomment following commented out lines to enable STDOUT while debugging.
hb WRITE_FLASH
commands
printf "%s",WRITE_BUF
c
end
```

The following sample programs use the standard output:

- Clock generator (CLG) [Common to S1C17M01/W22/W23]
- 16-bit PWM timer (T16B) [Only for S1C17W22/W23]
- ADC, Comparator [Only for S1C17W23]

## 3.4 Connecting with Target

Connect the PC where GNU17 was installed and the ICDmini with the USB cable, and connect the board equipped with an S1C17M01 or S1C17W22/W23 and ICDmini.

Note: When using ICDmini ver. 3.0 with GNU17 version 3, use the ICDmini Ver. 1.0, 1.1, and 2.0 compatible cable (S5U1C1700 1 W7200) to connect between the ICDmini and the target system.





(1) Connection example between ICDmini and S5U1C17M01T1

The figure below shows the connection example between ICDmini and S5U1C17M01T1. For more information, refer to the S5U1C17M01T1 Manual.



Figure 3.4.2 Connection diagram between ICDmini and S5U1C17M01T1

(2) Connection between ICDmini and S5U1C17W23T

The figure below shows the connection example between ICDmini and S5U1C17W23T. For more information, refer to the S5U1C17W23T Manual.



#### S5U1C17W23 evaluation board



## 3.5 Operating ICDmini and Target

### 3.5.1 When ICDmini ver. 2.0 is Used

Connect the target, ICDmini, and PC, reset them in the order below, and then confirm that the connection between the target and ICDmini is established. In addition, the setting of DIP Switch of ICDmini is as follows.

	Description	When S5U1C17M01T is	When S5U1C17W23T is
DIF SWICH	Description	connected	connected
1	Target CPU (C17 / C33)	OPEN个	OPEN↑
2	FLASH WRITER (OFF / WRITE)	<b>OPEN</b> 个	OPEN↑
3	FLASH WRITER (OFF / VERIFY)	<b>OPEN</b> 个	OPEN↑
4	DSIO LVL (ON / TRGET VCC)	<b>OPEN</b> 个	ON↓
5	DSIO LVL (3.3V / 1.8V)	<b>OPEN</b> 个	OPEN↑
6	CONNECTION DIAG (OFF / ON)	<b>OPEN</b> 个	OPEN↑
7	FW UPDATE MODE (OFF / ON)	<b>OPEN</b> 个	OPEN↑
8	FLASH VCC OUT (OFF / ON)	ON↓	ON↓







Setting for S5U1C17M01T

Setting for S5U1C17W23T

Figure 3.5.1.1 DIP switch of ICDmini

(1) Reset ICDmini

Set the DIP switch of ICDmini as the figure above and click the [RESET/START] button in ICDmini.

(2) Reset the target

Reset the target. For information on how to reset each target, refer to the target's manual.

(3) Confirm the established connection between the target and ICDmini

Confirm that the LEDs light up as follows in ICDmini.



Figure 3.5.1.2 LED display when ICDmini connection is established

## 3.5.2 When ICDmini ver. 3.0 is Used

Connect the target, ICDmini, and PC, and then confirm that the connection between the target and ICDmini is established.

(1) Confirm the established connection between the target and ICDmini

Confirm that the ICDmini LEDs light up as follows.



Figure 3.5.2.1 LED display when ICDmini connection is established

## 3.6 Building Project and Starting Debugger

This section describes how to build the sample program and start the debugger.

Notes: • For more information on how to build and start the debugger, refer to the S5U1C17001C Manual.

• Be aware that the IC may not operate normally if you terminate the program that is controlling the clocks or the related functions. For debugging the codes concerned, refer to the DCLK change mode command described in the S5U1C17001C Manual.

#### 3.6.1 When GNU17 version 2 is Used

(1) Build programs

In the GNU17's "C/C++ project" view, select the desired project to build. In the GNU17's [Project] menu, select [Build Project] to build the project. Select the desired project in the GNU17's "C/C++ project" view and select [Project's Build] in the context menu displayed by right-clicking the project to also build the project.

(2) Display debugger launch configuration dialog

Select [Debug Configuration...] in the GNU17's [Run] menu to display the [Debug Configurations] dialog. This dialog can be also displayed by clicking the [Debug] button in the toolbar.

(3) Select sample program to be launched

Select [GDB17 Debugger for <project name>] in the tree list.

💠 Debug Configurations				
Create, manage, and run configurations Configuration for debugging a GNU17 program.				
Ype filter text         C C/C++ Attach to Local Application         C C/C++ Local Application         C C/C++ Postmortem debugger         Image: C C/C++ Postmortem debugger         Image: ORUL7 debugging         Image: OBBLT Debugger for slc17xxx_xxx	Name:       GDB17 Debugger for s1c17xxx_xxx         Main       Image: Debugger       Image: Debugger         Project:       s1c17xxx_xxx         C/C++ Application:       s1c17xxx_xxx.elf         Image: Onnect process input output to a terminal.	Search Project)	Browse	
Filter matched 5 of 5 items		Apply	Revert	
0		Debug	Close	

#### (4) Launch debugger

Click the [Debug] button. The debugger gdb starts and executes prescribed command file.

#### 3.6.2 When GNU17 version 3 is Used

#### (1) Building

In the [Project Explorer] view, select the project to be built. Select [Build Project] from the [Project] menu (or the context menu that appears by right-clicking the project) to execute building.

(2) Displaying [Debug Configuration] dialog

Select [Debug Configurations...] from the GNU17 [Run] menu or the [Debug] dropdown list on the toolbar to display the [Debug Configurations] dialog.

(3) Configuring the debugger

Open the [Debugger] tab page and specify [gdbmini3.ini] for [GDB command file:]. ([gdbmini3.ini] has been specified by default in the sample project.)

Click the [Apply] button and then the [Debug] button to execute the specified command file.

Configurations			
Create, manage, and run configurations			
	Name: s1c17xxx_xxx_gnu17v3 Debug		
type filter text $A = C/C + + Application$	🗋 Main 🗠 Arguments 🗷 Environment 🎋 Debugger 🛛 🤄 Source 🔗 Refresh 🗖 Common		
s1c17xxx xxx gnu17v3	Debugger: MinGW gdb		
C/C++ Attach to Applica	Stop on startup at: main Advanced		
C/C++ Remote Applicati	i Debugger Options		
Launch Group	Main Shared Libraries		
	GDB debugger:\gdb		
	GDB command file: gdbmini3.ini		
	(Warning: Some commands in this file may interfere with the startup operation of the debugger, for example "run".)		
	GDB command set: Standard (Windows) 🔻		
	Protocol:		
	Verbose console mode		
	Use full file path to set breakpoints		
Filter matched 6 of 6 items	Using Legacy Create Process Launcher - <u>Select other</u> Revert Apply.		
0	Debug Close		

# 4. Details of Sample Software Function

This chapter describes the functions of the S1C17M01/W22/W23 sample software in detail.

## 4.1 I/O Port (P) [Common to S1C17M01/W22/W23]

#### 4.1.1 Sample Software Specification

This sample software works as follows by using I/O ports.

- When a port is set to input and the input signal becomes High or Low level, an interrupt occurs.
- The port is set to output and a High or Low level signal is output.

The table below lists the ports to be used and port names.

Setting	Port name
Input interrupt port	P01
Output port	P02

#### Table 4.1.1 I/O port setting list

#### 4.1.2 Hardware Conditions

This sample program runs in the OSC1 built-in oscillating circuit (32.768kHz) in the microcontroller.

For this sample program, connect the ports as follows in the microcontroller.



Figure 4.1.1 I/O port (P) sample software/hardware connection diagram

## 4.1.3 Operations Overview

- 1. Start the OSC1 oscillation and switch the system clock from IOSC to OSC1. Then sotp the IOSC.
- 2. Initialize the ports.
- 3. Set the P01 port to output and Output a Low level signal.
- 4. Set the P02 port to input and set it so that an interrupt occurs when the level changes from Low to High.
- 5. Output a High level signal from the P01 port.
- 6. Confirm that the P02 port is at High level after an interrupt in the P02 port.
- 7. Set the P02 port so that an interrupt occurs when the level changes from High to Low.
- 8. Output a Low level signal from the P01 port.
- 9. Confirm that the P02 port is at Low level after an interrupt in the P02 port.

## 4.2 Clock Generator (CLG) [Common to S1C17M01/W22/W23]

### 4.2.1 Sample Software Specification

This sample program works as follows by using OSC.

- Oscillate and stop OSC1.
- Oscillate and stop OSC3 (S1C17W22/W23 only). The setting of the oscillatory frequency is possible, too.
- Oscillate and stop IOSC.
- Change the system clock to OSC1.
- Change the system clock to OSC3.
- Change the system clock to IOSC.
- In the case of system clock is IOSC (S1C17M01/W22/W23) / OSC3 (only for S1C17W22/W23), do the transition control between SLEEP mode and RUN mode.
- Do the transition control between OSC1 HALT, IOSC RUN (S1C17M01/W22/W23, and OSC3 RUN (only for S1C17W22/W23).
- Change the system clock of OSC3 (only for S1C17W22/W23)

#### 4.2.2 Hardware Conditions

This sample program works by using the built-in oscillation (IOSC) in the microcontroller. Then change the system clock to OSC1 or OSC3 (only S1C17W22/W23). Therefore it needs transducer. For details, please refer to "Clock Generator (CLG)" in S1C17M01/S1C17W22/W23 technical manual.

#### 4.2.3 Operations Overview (S1C17M01)

This sample program starts to work while IOSC is working.

This sample program starts to work by using IOSC as a system clock. Note that the count value displayed below is estimated to be a little bigger than 327, the 10 millisecond count value of OSC1's oscillating frequency = 32.768kHz.

- 0. Start to oscillate OSC1, change the system clock to OSC1, and then stop the IOSC oscillation.
- 1. Stop CPU (HALT) and repeat to interrupt the timer three times per second. Each time a timer interrupt is received, start the IOSC oscillation, execute 10 milliseconds of loop, display a difference between the T16 timer count values before and after the loop on Simulated I/O, and stop IOSC.
- 2. Trim IOSC's oscillating frequency automatically based on the OSC1's oscillating clock.
- 3. Since this operation is the same as step 1, the automatic trimming result can be confirmed.
- 4. This step does nothing. This step is added only from a compatibility point of view with S1C17W22/W23's behavior.
- 5. After IOSC started to oscillate, stop CPU (SLEEP). In order to wake up CPU from the sleep mode, it is necessary to put the level "L" signal into port P04. When CPU wakes up and IOSC automatically starts to oscillate, execute 10 milliseconds of loop, display a difference between the T16 timer count values before and after the loop on Simulated I/O, and stop IOSC. This operation is repeated three times.

Finally, the program starts the IOSC oscillation, stops the OSC1 and OSC3 oscillations to finish the series of operations.

👸 Si	mulated I/O
<<<	Start CLG demonstration. >>>
***	Step 1-1 (IOSC) timer = 324 ***
***	Step 1-2 (IOSC) timer = 324 ***
***	Step 1-3 (IOSC) timer = 324 ***
<<<	Step 2: Start auto-trimming IOSCCLK by OSC1CLK. >>>
***	Step 3-1 (Adi-IOSC) timer = 327 ***
***	Step 3-2 (Adi-IOSC) timer = 327 ***
***	Step 3-3 (Adi-IOSC) timer = 327 ***
===	Now sleeping. Please input 'L' pulse to PO4. ===
***	Step 5-1 (Adj-IOSC) timer = 327 ***
===	Now sleeping. Please input 'L' pulse to PO4. ===
***	Step 5-2 (Adj-IOSC) timer = 327 ***
===	Now sleeping. Please input 'L' pulse to PO4. ===
***	Step 5-3 (Adi-IOSC) timer = 327 ***
<<<	Finish CLG demonstration. >>>

Figure 4.2.1 Display example of CLG\_OSC sample program screen (S1C17M01)

## 4.2.4 Operations Overview (S1C17W22/W23)

This sample program starts to work while IOSC is working.

This sample program starts to work by using IOSC as a system clock. Note that the count value displayed below is estimated to be a little bigger than 327, the 10 millisecond count value of OSC1's oscillating frequency = 32.768kHz.

- 0. Start to oscillate OSC1, change the system clock to OSC1, and then stop the IOSC oscillation.
- 1. Stop CPU (HALT) and repeat to interrupt the timer three times per second. Each time a timer interrupt is received, start the IOSC oscillation, execute 10 milliseconds of loop, display a difference between the T16 timer count values before and after the loop on Simulated I/O, and stop IOSC.
- 2. Trim IOSC's oscillating frequency automatically based on the OSC1's oscillating clock.
- 3. Since this operation is the same as step 1, the automatic trimming result can be confirmed.
- 4. Stop CPU (HALT) and repeat to interrupt the timer three times per second. Each time a timer interrupt is received, start the OSC3 oscillation (4MHz), execute 10 millisecond of loop, display a difference between the T16 timer count values before and after the loop on Simulated I/O, and stop OSC3.
- 5. After IOSC started to oscillate, stop CPU (SLEEP). In order to wake up CPU from the sleep mode, it is necessary to put the level "L" signal into port P04. For S5U1C17W23 (SVT17W23), it is possible to execute the action by pushing the push button SW4. When CPU wakes up and IOSC automatically starts to oscillate, execute 10 milliseconds of loop, display a difference between the T16 timer count values before and after the loop on Simulated I/O, and stop IOSC. This operation is repeated three times.
- 6. After OSC3 started to oscillate (4MHz), stop CPU (SLEEP). In order to wake up CPU from the sleep mode, it is necessary to put the level "L" signal into port P04. For S5U1C17W23 (SVT17W23), it is possible to execute the action by pushing the push button SW4. When CPU wakes up and OSC3 automatically starts to oscillate, execute 10 millisecond of loop, display a difference between the T16 timer count values before and after the loop on Simulated I/O, and stop OSC3. This operation is repeated three times.
- 7. At first, start the IOSC oscillation, execute 10 milliseconds of loop, display a difference between the T16 timer count values before and after the loop on Simulated I/O. Next, start the OSC3 oscillation (1MHz), stop the IOSC oscillation, execute 10 milliseconds of loop, display a difference between the T16 timer count values before and after the loop on Simulated I/O. Then, start the IOSC oscillation, change the clock, and stop the OSC3 oscillation in order to start the OSC3 oscillation at 4MHz. Then, start the OSC3 oscillation (4MHz), stop the IOSC oscillation, execute 10 milliseconds of loop, display a difference between the T16 timer count values before and after the loop on Simulated I/O.
- 8. Finally, the program starts the IOSC oscillation, stops the OSC1 and OSC3 oscillations to finish the series of operations.

👸 Si	mulated I/O	
$\langle \langle \langle$	Start CLG demonstration. >>>	
***	Step 1-1 (IOSC) timer = 330 ***	
***	Step 1-2 (IOSC) timer = 330 ***	
***	Step 1-3 (IOSC) timer = 330 ***	
<<<	Step 2: Start auto-trimming IOSCCLK by OSC1CLK.	>>>
***	Step 3-1 (Adj-IOSC) timer = 330 ***	
***	Step 3-2 (Adj-IOSC) timer = 330 ***	
***	Step 3-3 (Adj-IOSC) timer = 330 ***	
***	Step 4-1 (4MHz-OSC3)	
***	Step 4-2 (4MHz-OSC3)	
***	Step 4-3 (4MHz-OSC3)	
===	Now sleeping. Please press SW4. ===	
***	Step 5-1 (Adj-IOSC) timer = 330 ***	
===	Now sleeping. Please press SW4. ===	
***	Step 5-2 (Adj-IOSC) timer = 330 ***	
===	Now sleeping. Please press SW4. ===	
***	Step 5-3 (Adj-IOSC) timer = 330 ***	
===	Now sleeping. Please press SW4. ===	
***	Step 6-1 (4MHz-OSC3)	
===	Now sleeping. Please press SW4. ===	
***	Step 6-2 (4MHz-OSC3)	
====	Now sleeping. Please press SW4. ===	
***	Step 6-3 (4MHz-OSC3) timer = 336 ***	
***	Step 7-1 (Adj-IOSC) timer = 330 ***	
***	Step 7-2 (1MHz-OSC3) timer = 335 ***	
***	Step 7-3 (4MHz-OSC3) timer = 335 ***	
<u> </u>	Finish CLG demonstration. >>>	

Figure 4.2.2 Display example of CLG\_OSC sample program screen (S1C17W22/W23)

## 4.3 16-Bit Timer (T16) [Common to S1C17M01/W22/W23]

#### 4.3.1 Sample Software Specification

The 16-bit timer sample program works as follows by using 16-bit timer.

- Cause an interrupt in the 16-bit timer to get a counter value of the timer.
- When waiting for an interrupt, put CPU in a halt mode to reduce the power consumption.

#### 4.3.2 Hardware Conditions

This sample program runs in the IOSC built-in oscillating circuit in the microcontroller.

- S1C17M01: 7.37MHz
- S1C17W22/W23: 700kHz

#### 4.3.3 Operations Overview

- 1. Set the counter of the 16-bit timer.
- 2. Start the 16-bit timer and put CPU in a Halt state.
- 3. When an interrupt occurs in the 16-bit timer, release CPU from the Halt state.
- 4. Get the number of interrupts of the 16-bit timer.
- 5. When the number of interrupts of the 16-bit timer is less than 1000, put CPU in a Halt state again.
- 6. When the number of interrupts of the 16-bit timer is not less than 1000, stop the 16-bit timer and exit the sample program.

## 4.4 16-Bit PWM Timer (T16B) [Only for S1C17W22/W23]

#### 4.4.1 Sample Software Specification

The 16-bit PWM timer sample program works as follows by using 16-bit PWM timer.

- Cause a comparator interrupt in the 16-bit PWM timer.
- Cause a capture interrupt in the 16-bit PWM timer to get a counter value of the timer.
- When waiting for an interrupt, put CPU in a halt mode to reduce the power consumption.

#### 4.4.2 Hardware Conditions

This sample program runs in the IOSC built-in oscillating circuit in the microcontroller.

• S1C17W22/W23: 700kHz

#### 4.4.3 Operations Overview

- 1. Set the 16bit PWM timer as follows and start the T16-bit PWM timer.
  - Mode: Repeat up-count mode
  - Maximum counter value: 0x5000
  - Comparator/capture circuit 0: Comparator mode (compare buffer: 0x2000)
  - Comparator/capture circuit 1: Number of capture interrupts in capture mode (trigger signal: LOW)
- 2. Start the 16-bit PWM timer and put CPU in a Halt state.
- 3. When an interrupt occurs in the 16-bit PWM timer, release CPU from the Halt state.
- 4. Each time an interrupt occurs in the 16-bit PWM timer, get the number of interrupts below:
  - Number of compare interrupts
  - Number of capture interrupts
  - Number of maximum-count interrupts
  - Number of count-zero interrupts
- 5. When a compare interrupt occurs, set the trigger signal for capture to HIGH.
- 6. When a maximum-count interrupt occurs, set the trigger signal for capture to LOW.
- 7. When the number of maximum-count interrupts is less than 10, put CPU in a Halt state again.
- 8. When the number of maximum-count interrupts is not less than 10, stop the 16-bit timer, shows a count value when an interrupt occurred for Simulated I/O and exit the sample program.

🐮 Simulated I/O	
<pre>Simulated I/O </pre> <pre>  <pre> </pre> <pre> </pre> <pre> </pre></pre>	

Figure 4.4.1 T16B sample program screen (S1C17W22)

## 4.5 Real Time Clock (RTCA) [Common to S1C17M01/W22/W23]

#### 4.5.1 Sample Software Specification

The real time clock sample program works as follows by using real time clock.

- Set the time of real time clock.
- Get the time of real time clock.
- Get the number of interrupts of real time clock.
- Use theoretical regulation function.
- Use the stopwatch.

#### 4.5.2 Hardware Conditions

This sample program runs in the OSC1 built-in oscillating circuit (32.768 kHz) in the microcontroller.

#### 4.5.3 Operations Overview

- 1. Initialize the Real Time Clock.
- 2. Enable one- and a half-second interrupts of real time clock.
- 3. Set the theoretical regulation function of real time clock (theoretical regulation interval: 4,096sec, correction factor: -58.2ppm).
- 4. Set the date and time of real time clock to "Sat 99-12-31 23:59:51" and set the clock to 24-hour mode.
- 5. Start real time clock and put CPU in a Halt state.
- 6. When an interrupt occurs in real time clock, release CPU from the Halt state.
- 7. Get the number of one-second interrupts of real time clock.
- 8. When the number of one-second interrupts is less than 10, put CPU in a Halt state again.
- 9. When the number of one-second interrupts is not less than 10, set the clock to 12-hour mode and get the date and time of real time clock (the value is "Sun 00-01-01 12:00:01 AM").
- 10. Disable the one-second interrupt of real time clock.
- 11. Execute theoretical regulation at 4,096sec interval after real time clock starts.
- 12. Initialize the stopwatch.
- 13. Enable an interrupts of stopwatch.
- 14. Start stopwath and put CPU in a Halt state.
- 15. When an interrupt occurs in stopwatch, release CPU from the Halt state.
- 16. Get the number of 1 Hz interrupts of stopwatch.
- 17. When the number of 1 Hz interrupts is less than 10, put CPU in a Halt state again.
- 18. When the number of 1 Hz interrupts is not less than 10, read a stopwatch count (10 Hz digit, 100 Hz digit)
- 19. Stop the stopwatch and disable an interrupt of stopwatch.

## 4.6 Watchdog Timer (WDT) [Common to S1C17M01/W22/W23]

#### 4.6.1 Sample Software Specification

The watchdog timer sample program works as follows by using the watchdog timer.

- Confirm that the watchdog timer is cleared.
- Cause a reset interrupt with the watchdog timer.

#### 4.6.2 Hardware Conditions

This sample program runs in the OSC1 built-in oscillating circuit (32.768 kHz) in the microcontroller.

#### 4.6.3 Operations Overview

- 1. Start the watchdog timer and real time clock.
- 2. If one-second interrupt occurs in real time clock, reset the watchdog timer.
- 3. If one-second interrupt occurs 10 times in real time clock, stop real time clock.
- 4. If a reset interrupt occurs with the watchdog timer, the processing returns to the top (boot.c) of this sample program.

## 4.7 UART (UART) [Common to S1C17M01/W22/W23]

### 4.7.1 Sample Software Specification

The UART sample program works as follows by using UART.

- Send data by using UART.
- Receive data by using UART.

#### 4.7.2 Hardware Conditions

This sample program runs in the IOSC built-in oscillating circuit in the microcontroller.

- S1C17M01: 7.37MHz
- S1C17W22/W23: 700kHz

Connect the evaluation boards where the UART master/slave sample programs are installed. Launch the slave sample program first. Connect each port as follows:



Figure 4.7.1 Hardware connection diagram for UART sample program

#### 4.7.3 Operations Overview

#### 4.7.3.1 Operations Overview of Master Sample

- 1. Initialize the UART ports with the values below:
  - Communication speed : S1C17M01: 460800bps / S1C17W22/W23: 43750bps
  - Data length : 8bit
  - Stop bit : 1bit
  - Parity : None
- 2. Send the data from "A (0x41)" to "Z (0x5A)" and "\$0" to the slave.
- 3. Receive the 27byte of data from the slave.
- 4. Compare whether the received data is the same as the sent data and exit the sample program.

#### 4.7.3.2 Operations Overview of Slave Sample

- 1. Initialize the UART ports with the values below:
  - Communication speed :S1C17M01: 460800bps / S1C17W22/W23: 43750bps
  - Data length : 8bit
  - Stop bit : 1bit
  - Parity : None
- 2. Receive the 27byte of data from the master.
- 3. Send the data from "A (0x41)" to "Z (0x5A)" and "¥0" to the master.
- 4. Compare whether the received data is the same as the sent data and exit the sample program.

## 4.8 SPI (SPI) [Common to S1C17M01/W22/W23]

#### 4.8.1 Sample Software Specification

The SPI sample program works as follows by using SPI.

- Send data by using SPI.
- Receive data by using SPI.

#### 4.8.2 Hardware Conditions

This sample program runs in the IOSC built-in oscillating circuit in the microcontroller.

- S1C17M01: 7.37MHz
- S1C17W22/W23: 700kHz

Connect the evaluation boards where the SPI master/slave sample programs are installed. Launch the slave sample program first. Connect each port as follows:



Figure 4.8.1 Hardware connection diagram for SPI master/slave sample programs

#### 4.8.3 Operations Overview

#### 4.8.3.1 Operations Overview of Master Sample

- 1. Initialize the SPI ports with the values below:
  - Data length : 8bit
  - Data format : MSB first
- 2. Send the data from "A (0x41)" to "Z (0x5A)" and "\$0" to the slave.
- 3. Receive the 27byte of data from the slave.
- 4. Compare whether the received data is the same as the sent data and exit the sample program.

#### 4.8.3.2 Operations Overview of Slave Sample

- 1. Initialize the SPI ports with the values below:
  - Data length : 8bit
  - Data format : MSB first
- 2. Receive the 27byte of data from the master.
- 3. Send the data from "A (0x41)" to "Z (0x5A)" and "¥0" to the master.
- 4. Compare whether the received data is the same as the sent data and exit the sample program.

## 4.9 I2C (I2C) [Common to S1C17M01/W22/W23]

#### 4.9.1 Sample Software Specification

The I2C sample program works as follows by using I2C.

- Send data by using I2C.
- Receive data by using I2C.

#### 4.9.2 Hardware Conditions

This sample program runs in the IOSC built-in oscillating circuit in the microcontroller.

- S1C17M01: 7.37MHz
- S1C17W22/W23: 700kHz

Connect the evaluation boards where the I2C master/slave sample programs are installed. Launch the slave sample program first. Connect each port as follows:



Figure 4.9.1 Hardware connection diagram for I2C master/slave sample programs

#### 4.9.3 Operations Overview

#### 4.9.3.1 Operations Overview of Master Sample

- 1. Initialize the I2C port with the value below:
  - Communication speed (S1C17M01) : 368500bps
  - Communication speed (S1C17W22/W23) : 35000bps
- 2. Send the data from "A (0x41)" to "Z (0x5A)" and "\$0" to the slave.
- 3. Receive the 27byte of data from the slave.
- 4. Compare whether the received data is the same as the sent data and exit the sample program.

#### 4.9.3.2 Operations Overview of Slave Sample

- 1. Initialize the I2C ports with the values below:
  - Address mode : 7bit
  - Slave address : 0x2A
  - General call : Invalid
- 2. Receive the 27byte of data from the master.
- 3. Send the data from "A (0x41)" to "Z (0x5A)" and "¥0" to the master.
- 4. Compare whether the received data is the same as the sent data and exit the sample program.

## 4.10 LCD driver (LCD8A) [Only for S1C17M01]

#### 4.10.1 Sample Software Specification

The LCD driver sample program is intended for S5U1C17M01T1. This sample program works as follows by using LCD8A.

- Turn on/off all lamps in normal display.
- Turn on/off all lamps with all switch function.

#### 4.10.2 Hardware Conditions

This sample program is intended for S5U1C17M01T1. For information on the connection with LCD panel, etc., refer to S5U1C17M01T1 Manual. This sample program runs in the OSC1 built-in oscillating circuit (32.768 kHz) in the microcontroller.

#### 4.10.3 Operations Overview

- 1. Turn on all lamps for two seconds.
- 2. Turn off all lamps for two seconds.
- 3. Display "00000000" for two seconds on the segment.
- 4. Display "12345678" for two seconds on the segment.
- 5. Turn on the "battery warning" lamp for two seconds.
- 6. Turn on the "overflow warning" lamp for two seconds.
- 7. Turn on the "water-leak warning (up)" lamp for two seconds.
- 8. Turn on the "water-leak warning (down)" lamp for two seconds.
- 9. Turn on the "water-leak warning (up-down)" lamp for two seconds.
- 10. Turn on the "reverse flow warning (inside)" lamp for two seconds.
- 11. Turn on the "reverse flow warning (outside)" lamp for two seconds.
- 12. Turn on the "reverse flow warning (inside-outside)" lamp for two seconds.
- 13. Turn on the "unit ("m3/h")" lamp for two seconds.
- 14. Turn on the "communication" lamp for two seconds.
- 15. Turn on the "pilot" lamp for two seconds.
- 16. Turn off the segment for two seconds.
- 17. Display "Error" for two seconds on the segment.
- 18. Display "87654321" for two seconds on the segment.
- 19. Turn off LCD and exit the sample program.

# 4.11 LCD driver (LCD24A) [Only for S1C17W22]

## 4.11.1 Sample Software Specification

The LCD driver sample program is intended for S5U1C17W23T. This sample program works as follows by using LCD24A.

- Turn on/off all lamps in normal display.
- Turn on/off all lamps with all switch function.

## 4.11.2 Hardware Conditions

This sample program is intended for S5U1C17W23T. For information on the connection with LCD panel, etc., refer to S5U1C17W23T Manual. This sample program runs in the OSC1 built-in oscillating circuit (32.768 kHz) in the microcontroller.

#### 4.11.3 Operations Overview

- 1. Turn on all lamps for two seconds.
- 2. Turn off all lamps for two seconds.
- 3. Set a check pattern (small) in the display area 0.
- 4. Select the display area 0 and display the area for two seconds in normal mode.
- 5. Reverse display the area for two seconds.
- 6. Set a check pattern (medium) in the display area 1.
- 7. Select the display area 1 and display it for two seconds in normal mode.
- 8. Reverse display the area for two seconds.
- 9. Set a check pattern (large) in the display area 0.
- 10. Select the display area 0 and display it for two seconds in normal mode.
- 11. Reverse display the area for two seconds.
- 12. Turn off LCD and exit the sample program.

## 4.12 R/F Converter (RFC) [Common to S1C17M01/W22/W23]

#### 4.12.1 Sample Software Specification

The R/F converter sample program works as follows by using the R/F converter.

• Make the sensor's resistance CR oscillate, count the oscillation clock, and convert the oscillation into digital value.

#### 4.12.2 Hardware Conditions

This sample program runs in the OSC1 built-in oscillating circuit (32.768 kHz) in the microcontroller. Before the use of this sample program, connect the board as follows:



Figure 4.12.1 Hardware connection diagram for R/F converter sample program (S1C17M01)



Figure 4.12.2 Hardware connection diagram for R/F converter sample program (S1C17W22/W23)

## 4.12.3 Operations Overview

- 1. Set external clock input mode and oscillation mode of RFC.
- Initialize the measurement counter of R/F converter with 0x00fc0000 and start the measurement. (measurement time : about 8 sec)
- 3. Get the measurement values from the reference and sensor oscillations and exit the sample program.

# 4.13 Sound Generator (SNDA) [Only for S1C17W22/W23]

#### 4.13.1 Sample Software Specification

The sound generator sample program works as follows by using the sound generator.

- Sound buzzer with normal buzzer mode function.
- Sound buzzer with one-shot buzzer mode function.
- Sound buzzer with melody mode function.

#### 4.13.2 Hardware Conditions

This sample program runs in the OSC1 built-in oscillating circuit (32.768 kHz) in the microcontroller. Before the use of this sample program, connect the board as follows:



Figure 4.13.1 Hardware connection diagram for sound generator sample program

#### 4.13.3 Operations Overview

- 1. Sound buzzer for two seconds in normal buzzer mode.
- 2. Sound buzzer for a three times in one-shot buzzer mode.
- 3. Output eighth-note single tones of the scales [C4], [D4], [E4], [F4], [G4], [A4], [B4], and [C5] in melody mode and exit the sample program.

## 4.14 MR Sensor Controller (AMRC) [Only for S1C17M01]

#### 4.14.1 Sample Software Specification

The MR sensor controller sample program works as follows by using the MR sensor controller.

- Count the number of passings of the magnet by using half-bridge MR sensor.
- Count and memorize the number of passings of the magnet for a certain period of time to get a value corresponding to the speed.
- Output the signals for monitoring status to the pins below.
  - O P00 : CMPIN0P < CMPIN0N: Output LOW / CMPIN0P > CMPIN0N: Output HIGH
  - O P01 : Low sample rate: Output LOW / High sample rate: Output HIGH
  - O EVPLS (P07) : Pilot pulse for detecting the change of magnetic field

#### 4.14.2 Hardware Conditions

This sample program runs in the OSC1 built-in oscillating circuit (32.768 kHz) in the microcontroller. Before the use of this sample program, connect the board as follows:



Figure 4.14.1 Hardware connection diagram for MR sensor sample program (S1C17M01)

Tune the dial of semi-fixed resistance as follows by monitoring the voltage level at the pin P00 and confirm that the output value at the pin P00 changes according to whether magnetic field is applied to the sensor or not.

Resistance between CMPIN0N & GND	0 <> Maximum
Voltage level at pin P00	НННННННННННННЦLLLLLLLLLLLLLLLLL

## $\uparrow$ Align with this position

#### 4.14.3 Operations Overview

- 1. In normal condition, it is checked at a frequency of 32 times per second whether the applied magnetic field is changed in the MR sensor. (action when magnetic field change is not detected)
- 2. If it is confirmed that the applied magnetic field is changed in the MR sensor, the applied magnetic field is checked at a frequency of 1024 times per second. (if magnetic field change is detected, the sampling frequency increases)
- 3. If it is confirmed continuously for two seconds that the applied magnetic field is not changed, it moves to the normal mode where it is checked at a frequency of 32 times per second whether the applied magnetic field is changed. (if magnetic field is considered not changed, it returns to normal sampling frequency)
- 4. The components corresponding to the speed can be obtained by using the values of hbmrInfo.cntBuff[].

# 4.15 Power Supply Voltage Detection Circuit (SVD) [Common to S1C17M01/W22/W23]

#### 4.15.1 Sample Software Specification

The power supply voltage detection circuit sample program works as follows by using the power supply voltage detection circuit.

• In the power supply voltage detection circuit, compare the power supply voltage and the comparison voltage.

#### 4.15.2 Hardware Conditions

This sample program runs in the OSC1 built-in oscillating circuit (32.768 kHz) in the microcontroller. Before the use of this sample program, connect the board as follows:





#### 4.15.3 Operations Overview

- 1. Set and start real time clock so that an interrupt occurs every second.
- 2. Set and start the power supply voltage detection circuit so that the voltage drop can be detected at 2.7V or less voltage.
- 3. Check every second whether the voltage drop occurred.
- 4. Measure the number of voltage drops for 10seconds and exit the sample program.

## 4.16 Power Generator (PWG2) [Only for S1C17W22/W23]

#### 4.16.1 Sample Software Specification

The power generator sample program works as follows by using the power generator.

• Change power saving mode.

#### 4.16.2 Hardware Conditions

This sample program runs in the OSC1 built-in oscillating circuit (32.768 kHz) in the microcontroller. Before the use of this sample program, connect the board as follows:



Figure 4.16.1 Hardware connection diagram for power generator sample program

#### 4.16.3 Operations Overview

- 1. Launch OSC1 and stop all other clocks.
- 2. Set and start the power supply voltage detection circuit so that the voltage drop can be detected at 2.7V or less voltage.
- 3. Set and start real time clock so that an interrupt occurs every second.
- 4. Put the power generator in normal mode.
- 5. After 10seconds, put the power generator in economy mode.
- 6. If a voltage drop (not more than 2.7V) is not detected after 10seconds, put the power generator in super economy mode.
- 7. After 10seconds, put the power generator in auto mode.
- 8. After 10seconds, exit the sample program.

## 4.17 EEPROM [Only for S1C17M01]

#### 4.17.1 Sample Software Specification

The EEPROM sample program is intended for S5U1C17M01T1. This sample program works as follows by using I2C.

- Write data into EEPROM.
- Read data from EEPROM.

#### 4.17.2 Hardware Conditions

This sample program is intended for S5U1C17M01T1. For information on the connection with EEPROM, etc., refer to S5U1C17M01T1 Manual.



Figure 4.17.1 Hardware connection diagram for EEPROM sample program

This sample program runs in the IOSC built-in oscillating circuit in the microcontroller.

• S1C17M01: 7.37MHz

#### 4.17.3 Operations Overview

- 1. Initialize the I2C port with the value below:
  - Communication speed : S1C17M01: 368500 bps
- 2. Set the port P57 to GPIO and HIGH (clear write protect).
- 3. Write data as follows into EEPROM:
  - In I2C, send the address (0x0000) for writing data to the slave (address: 0x50).
  - In I2C, send 5byte of data.
- 4. Read data as follows from EEPROM:
  - In I2C, send the address (0x0000) for reading data to the slave (address: 0x50).
  - In I2C, receive 5byte of data.
- 5. Compare whether the received data is the same as the sent data and exit the sample program.

## 4.18 ADC, Comparator [Only for S1C17W23]

#### 4.18.1 Sample Software Specification

The ADC / Comparator is the sample program that targeted the following using S5U1C17W23T (Fig, 4.18.1). S5U1C17W23T connects exeternal push switch (SW1~SW4), 7 registance, and oe condenser. This sample program works as follows by using ADC / Comparatpr.

- A pressed Switch is discriminated and if corresponding Switch is found, the result is output to the simulated I/O.
- Input the same input voltage into a comparator and it judges whether midpoint potential is high or low.

#### 4.18.2 Hardware Conditions

This sample program targeted the following using S5U1C17W23T. For details of connection, please refer to the Manual of S5U1C17W23T.



Fig. 4.18.1 ADC, Comparator sample program exeternal connection circuit

#### 4.18.3 Operations Overview

- 1 The A/D converter uses T16 Ch. 3 for a conversion clock. The converter repeats the behavior that the A/D conversion is triggered by an underflow of T16 Ch. 3 occurring every second and an interrupt occurs upon termination of the conversion.
- 2 When an overwrite error interrupt occurs in the A/D converter, the A/D conversion is retried. When an A/D conversion completion interrupt occurs, the program reads the ADIN00 and ADIN01 values and the judgment from the comparator, displays these results on Simulated I/O and also the switch pushed according to the ADIN00 value. Here, this sample software does not support the case when more than one switch is pushed at the same time.
- 3 If you are concerned about an impact from noise, add  $0.1\mu$ F or so of capacitor between ADIN00 and GND.

💏 Simulated I/O			- U ×
SW OFF: AD(0)=3301 SW OFF: AD(0)=3303 SW1 ON: AD(0)= 0 SW OFF: AD(0)=3303 SW2 ON: AD(0)=1666 SW OFF: AD(0)=3305 SW3 ON: AD(0)=2370 SW OFF: AD(0)=3305 SW4 ON: AD(0)=2761 SW OFF: AD(0)=3302 SW OFF: AD(0)=3307	AD(1)=2044 AD(1)=2044 AD(1)=2044 AD(1)=2044 AD(1)=2044 AD(1)=2044 AD(1)=2044 AD(1)=2044 AD(1)=2044 AD(1)=2044 AD(1)=2044	COMP=1 COMP=0 COMP=1 COMP=0 COMP=1 COMP=1 COMP=1 COMP=1 COMP=1 COMP=1	

Fig. 4.18.2 ADC, Comparator sample programscreen (S1C17W23)

## 4.19 REMC [Common to S1C17W22/W23]

#### 4.19.1 Sample Software Specification

The REMC sample program generates signals for infrared ray remote-controller by using REMC mounted on the S1C17W23 evaluation board (SVT17W23). This sample program performs the following operations by using REMC.

- Move to a sleep mode after initialization and wait for interrupts triggered by push switches SW1 to SW4 (connected to P07 to P04).
- When an interrupt is caused by SW1 to SW4, analyze which switch was pushed and accordingly generate a signal (frame signal) for infrared ray remote-controller on REMC. Then, activate the T16 Ch.0 timer and check the switch status after about 108ms.
- If the same key was pushed consecutively when an interrupt occurred at the T16 Ch.0 timer, generate a repeat signal and set the T16 Ch.0 timer so that the switch status is checked again after about 108ms. Otherwise, stop the T16 Ch.0 timer and REMC, enter into a sleep mode, and wait for interrupts triggered by switches SW1 to SW4.

#### 4.19.2 Hardware Conditions

This sample program is for the S1C17W23 evaluation board (SVT17W23). For information on a connection to the circuit as shown in Figure 4.19.1, refer to the SVT17W23's manual.



Figure 4.19.1 Infrared-emitting diode connection circuit example for REMC sample program

#### 4.19.3 Operations Overview

- 1 As communication formats for infrared ray remote-controller, there are NEC, Association for Electric Home Appliances and SONY formats, and this sample software uses the NEC format.
- 2 The NEC format outline is as follows and Figure 4.19.2 also shows the NEC format.

Carrier: Infrared ray ( $\lambda p = 940$ nm) Sub carrier: fsc = 38kHz, 1/3duty T = 562 $\mu$ s Fixed length frame (32bit) 16bit customer code 8bit data + 8bit reverse data



Figure 4.19.2 Signal waveform of NEC format

- 3 REMC determines the data waveform shape by two parameters: APLEN (data signal duty) and DBLEN (data signal cycle). Each of APLEN and DBLEN defines the waveform shape with 34 frame signals and 2 repeat signals and allocates the leader, customer code, and repeat signals common to push switches SW1 to SW4 at initialization. Since the 16 values at data part may vary according to SW1 to SW4, the data values are allocated when an interrupt occurs by pushing a switch.
- 4 This sample program uses the OSC3 behavior at 4MHz. Set a GPIO mode for push switches SW1 to SW4, allocate ports for REMO, initialize T16 Ch.0, and enter into a sleep mode to wait for interrupts caused by pushing switches SW1 to SW4.
- 5 When an interrupt occurs, analyze which switch was pushed and allocate APLEN and DBLEN values in data part according to the switch pushed. Since REMC uses a buffer mode, activate REMC after initialization. Also, activate T16 Ch.0 and generate a T16 Ch.0 interrupt after about 108ms.
- 6 When a compare DB interrupt occurs at REMC, write the following APLEN and DBLEN data into register. When writing last but one piece of data, change REMC to a one-shot mode to prevent the whisker-like signal output. At the last data, stop the REMC operation.
- 7 When a T16 Ch.0 interrupt occurred, check whether the same switch SW1 to SW4 was pushed. If the same switch was pushed, set the register values of REMC so that a repeat waveform is generated, initialize REMC before activation, and activate REMC. Otherwise, stop the T16 Ch.0 operation.

# **Revision History**

				Attachment-1
Rev. No.	Date	Page	Category	Contents
Rev. 1.0	2013/12/5	All	new	
Rev. 1.1	2014/7/25	Page 12	Addition	Added a note to terminate the program that controls the clocks or related functions.
		Page 13	Modify	Modified the evaluation board name in Figure 4.1.1.
		Page 21	Replacement	Replaced Figure 4.4.1 according to the corrected T16B sample driver.
		Page 23	Modify	Replaced "NMI interrupt" with "reset interrupt." Modified the description in Operations Overview No. 4.
		Page 37	Modify	Replaced [only for S1C17W23] with [Common to S1C17W22/W23] as a target model was added.
Rev. 1.2	2015/12/8	Overall	Addition	Added descriptions relating to the operating environment (GNU17 version 2/version 3, ICDmini ver. 2.0/ver. 3.0), as a new operating environment has been supported.

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